



# KA1020-01 UxV/35™ Complete 18650 Quadcopter Power Wing Datasheet

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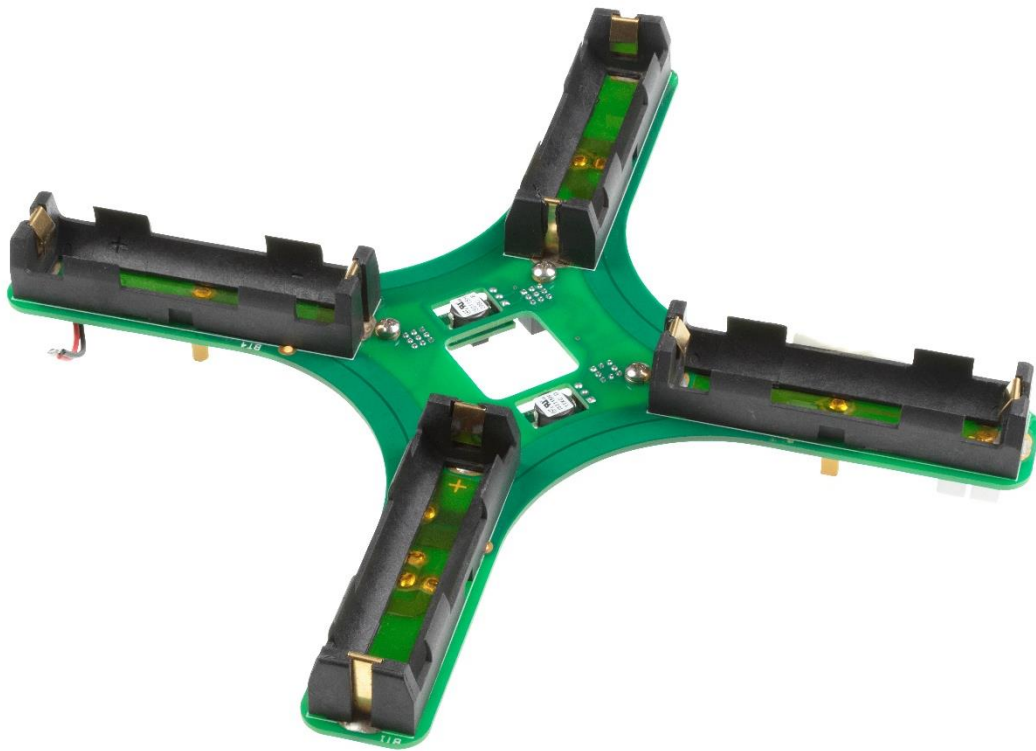
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## Description of the Board

This Power wing is designed specifically for usage of the UxV/35™ as a quadcopter.

The 18650 batteries are arranged in a 4S configuration. The power is turned on and off with a button. An external safety enable is required to enable the pre-routed motor power to the ESCs. UxV/35™ stack power is always available when the power is turned on. PI filtering is used for the generation of 5v and 3.3v power to the stack.



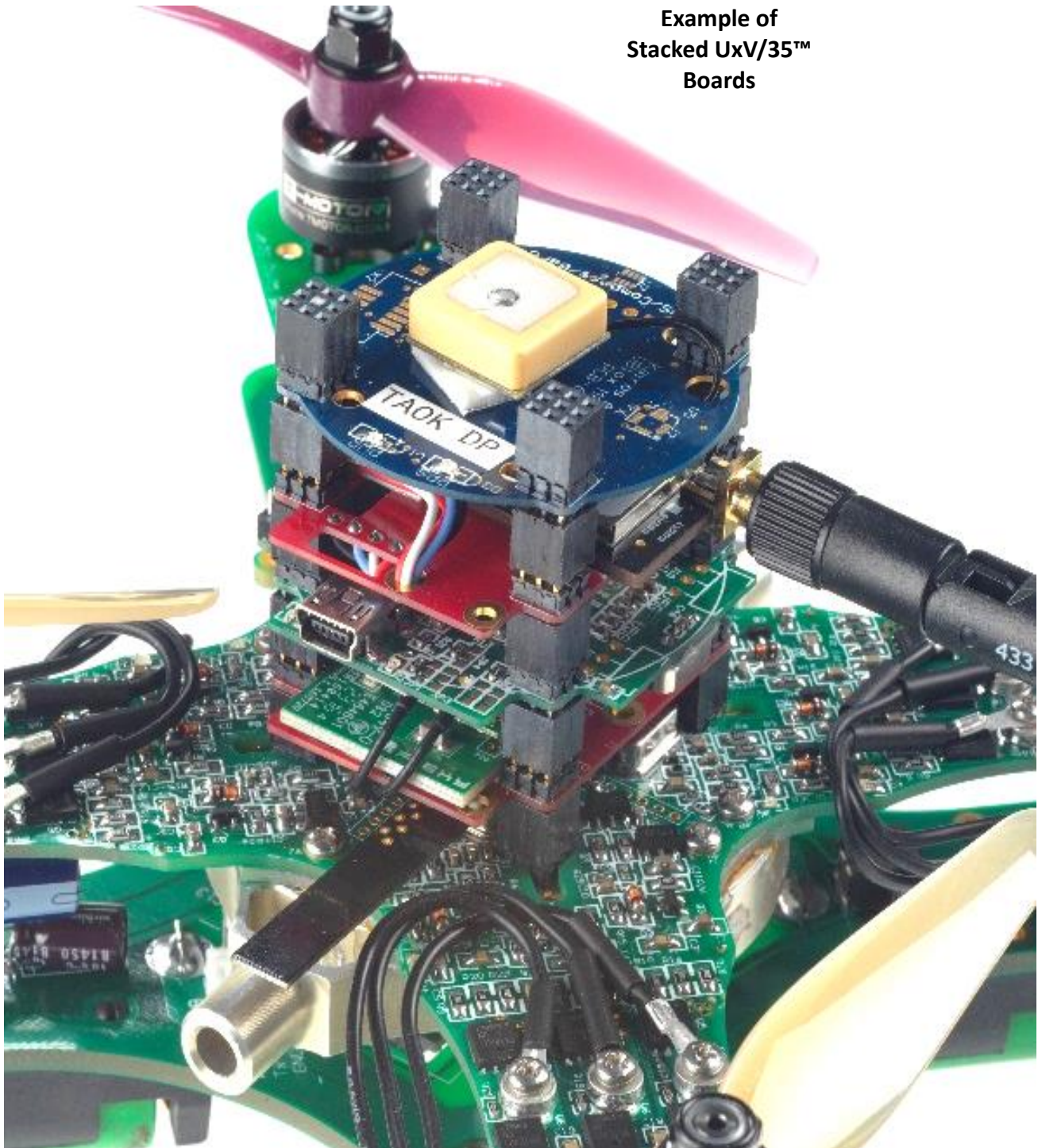


**Example of  
fully assembled quadcopter**





Example of  
Stacked UxV/35™  
Boards

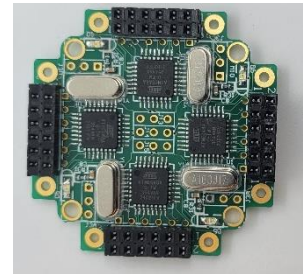
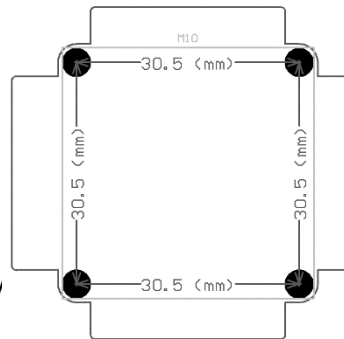




## Defining the UxV/35™ standard

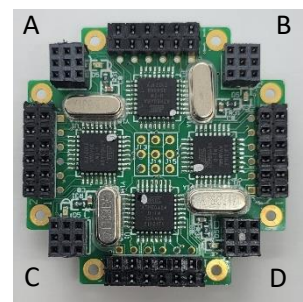
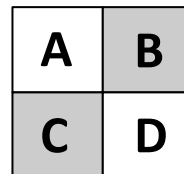
The UxV/35™ Bus is divided into 4 quadrants, located at the 4 corners of the 30.5mm square board (ad hoc industry standard). The four quadrants are assigned signal groups as follows:

- A Servo Signals
- B I2C and General-Purpose Signals
- C Power and Power Monitoring, Analogs, Safety
- D Serial Signals



The groups are arranged on the board in the four corners. Each of the groups is assigned a letter in the range A – D. The groups are assigned as follows:

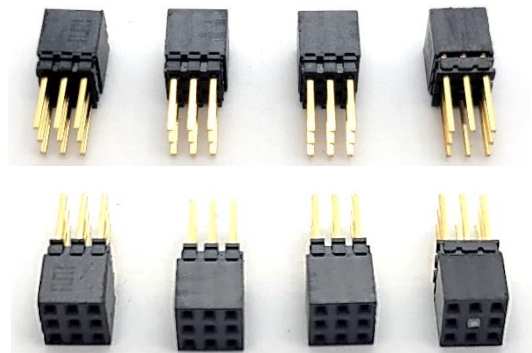
- Group A Upper Left
- Group B Upper Right
- Group C Lower Left
- Group D Lower Right



With Kairos assistance, Samtec developed a set of connectors based on a 2mm grid in a 3 x 3 pinning format. Groups A, B, and C use the full 9-pin load. Group D uses an 8-pin load. Without the middle pin, Group D becomes the key.

These connectors stack and nest forming a columnar bus of 9 pins. The concept is similar to that of PC/104. Samtec assigned these P/Ns:

Samtec P/N	Connector Type
ASP-232112-05	8-pin loaded, 2mm 3x3 format, center key
ASP-232112-06	9-pin loaded, 2mm 3x3 format



Each group is numbered 1 through 9, left to right, starting in the upper left, and proceeding across and down. The group precedes the pin number when referencing a pin. The pins of the four groups are numbered as follows:

A1	A2	A3
A4	A5	A6
A7	A8	A9

B1	B2	B3
B4	B5	B6
B7	B8	B9

C1	C2	C3
C4	C5	C6
C7	C8	C9

D1	D2	D3
D4		D6
D7	D8	D9



Each of the group's A-D are assigned signals that relate to the control and monitoring of unmanned ground, air, and surface vehicles. The group assignments are as follows:

- A1 – Servo Output 1 Assigned to S1
- A2 – Servo Output 2 Assigned to S2
- A3 – Servo Output 3 Assigned to S3
- A4 – Servo Output 4 Assigned to S4
- A5 – Servo Output 5
- A6 – Servo Output 6
- A7 – Servo Output 7
- A8 – Servo Output 8
- A9 – SBUS Signal Serial Receive Channel E (input to FC)
  
- B1 – Primary I2C Clock (SCL)
- B2 – Primary I2C Data (SDA)
- B3 – Secondary I2C Clock (SCL)
- B4 – Secondary I2C Data (SDA)
- B5 – GP1 Video In from Camera or Secondary SPI MISO
- B6 – GP2 Video Out from Text Overlay or Secondary SPI MOSI
- B7 – GP3 Serial Transmit Channel F (output from FC) or Secondary SPI SCLK
- B8 – GP4 Serial Receive Channel F (input to FC) or Secondary SPI Chip Select #1
- B9 – GP5 Serial Transmit Channel E (output from FC) or Secondary SPI Chip Select #2
  
- C1 – Battery Voltage (3S or 4S) Battery +
- C2 – Ground Battery –
- C3 – Radio Signal Strength Indicator 0-3.3v (RSSI)
- C4 – Analog Current Usage Indicator, 0-3.3v (Ain)
- C5 – Return to Home
- C6 – 3.3V Generated from Battery input (1 amp)
- C7 – Reset
- C8 – Pause
- C9 – +5V Generated from Battery input (1 amp)
  
- D1 – Serial Transmit Channel A (output from FC)
- D2 – Serial Receive Channel A (input to FC)
- D3 – Serial Transmit Channel B (output from FC)
- D4 – Serial Receive Channel B (input to FC)
- D5 – Pin not Present, used as key
- D6 – Serial Transmit Channel C (output from FC)
- D7 – Serial Receive Channel C (input to FC)
- D8 – Serial Transmit Channel D (output from FC)
- D9 – Serial Receive Channel D (input to FC)



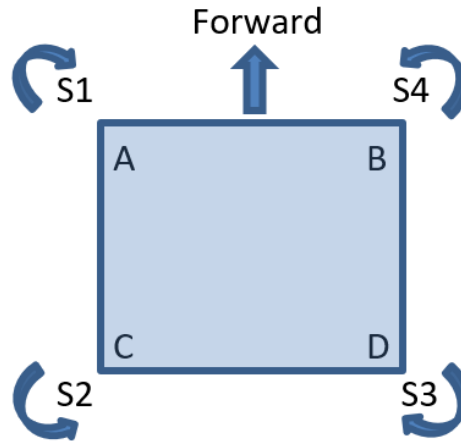


# Suggested Pin Assignments for UAV, UGV, and USV

Although autopilots for uncrewed systems have significant configuration abilities (mostly I/O), these suggested assignments enable lower-skilled interoperability:

## UAV – Quadcopter

- S1 Forward Left Rotor, CW
- S2 Rear Left Rotor, CCW
- S3 Rear Right Rotor, CW
- S4 Front Right Rotor, CCW
- TxC/RxC GPS
- TxB/RxB MavLink
- TxA/RxA Commander/Swarm
- I2CA Baro, Compass



## UAV – Fixed Wing

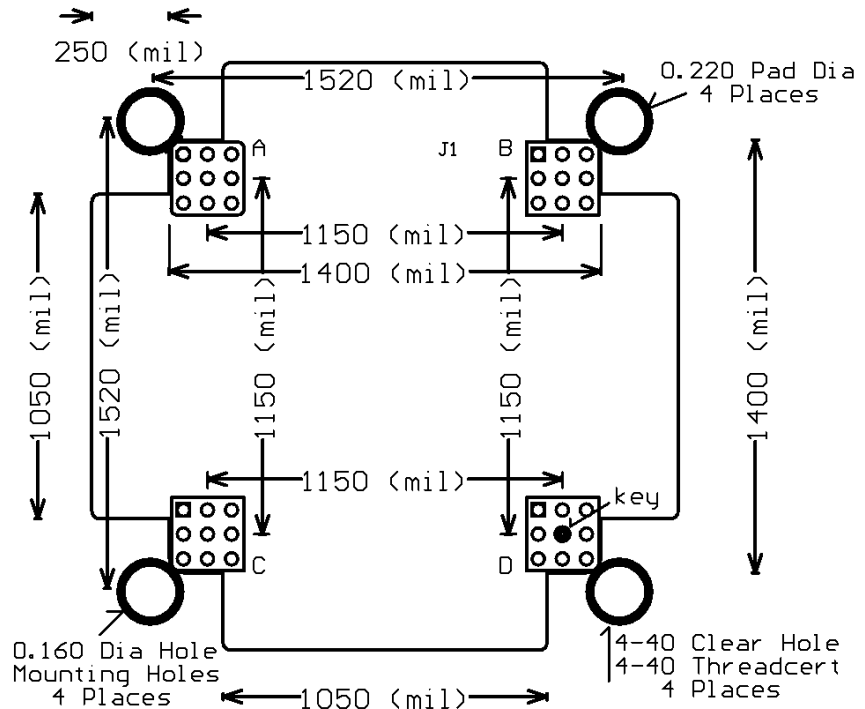
- S1 Elevator
- S2 Flaperon Right
- S3 Flaperon Left
- S4 Throttle ESC
- TxC/RxC GPS
- TxB/RxB MavLink
- I2CA Baro, Compass
- TxA/RxA Commander

## UGV

- S1 Steering
- S2 Throttle
- S3 Brake
- S4 Transmission
- TxC/RxC GPS
- I2CA Compass
- TxA/RxA Commander

## USV

- S1 Steering
- S2 Throttle
- TxC/RxC GPS
- I2CA Compass
- TxA/RxA Commander





## Country of Origin

Kairos82nd uses the color of the PCB to assist in the determination of country of origin. **One hundred percent of Kairos82nd UxV/35™ components are manufactured in Salt Lake City, Utah. The PCBs are sourced and assembled locally. The firmware on these boards is source code managed by Kairos82nd or is available as open source.**

All Kairos82nd UxV/35™ PCB boards that are **Blue** or **Green** are built with components sourced from domestic and global foundries. Any firmware is owned, managed, or controlled by Kairos82nd.

Any of our PCBs that are **Red** indicate that they may contain components from a country of origin that is not acceptable for usage by the U.S. Government without a waiver. All interoperability boards are **Red** because they can be adapted to and used with third party boards where Kairos82nd cannot manage the country of origin.

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